

ME243: Assignment 2

Due: 28/8/14

1. Prove using indicial notation that

$$\det(\mathbf{RS}) = \det(\mathbf{R}) \det(\mathbf{S})$$

2. Using the relation $\mathbf{cof} \mathbf{T} = (\det \mathbf{T}) \mathbf{T}^{-T}$ for an invertible \mathbf{T} , compute the eigenvalues of $\mathbf{cof} \mathbf{T}$ in terms of the eigenvalues of \mathbf{T} (denoted by λ_1, λ_2 and λ_3). (Hint: First find the eigenvalues of $(\mathbf{cof} \mathbf{T})^T$, and then use the fact that $\det \mathbf{S} = \det \mathbf{S}^T$.)
3. Show that if \mathbf{R} and \mathbf{S} are second-order tensors, then

$$\det \mathbf{R} = \frac{1}{3} \mathbf{R} : \mathbf{cof} \mathbf{R},$$
$$\det(\mathbf{R} + \mathbf{S}) = \det \mathbf{R} + \mathbf{cof} \mathbf{R} : \mathbf{S} + \mathbf{R} : \mathbf{cof} \mathbf{S} + \det \mathbf{S}.$$

4. Using *direct notation* show that (also verify using indicial notation)

$$\begin{aligned}(\mathbf{a} \otimes \mathbf{b})^T &= \mathbf{b} \otimes \mathbf{a}, \\(\mathbf{a} \otimes \mathbf{b})(\mathbf{c} \otimes \mathbf{d}) &= (\mathbf{b} \cdot \mathbf{c}) \mathbf{a} \otimes \mathbf{d}, \\(\mathbf{a} \otimes \mathbf{b}) : (\mathbf{u} \otimes \mathbf{v}) &= (\mathbf{a} \cdot \mathbf{u})(\mathbf{b} \cdot \mathbf{v}), \\ \mathbf{T}(\mathbf{a} \otimes \mathbf{b}) &= (\mathbf{T}\mathbf{a}) \otimes \mathbf{b}, \\(\mathbf{a} \otimes \mathbf{b})\mathbf{T} &= \mathbf{a} \otimes (\mathbf{T}^T \mathbf{b}).\end{aligned}$$

Use any of the above results to show that for a symmetric tensor, \mathbf{S} , the spectral decompositions of \mathbf{S}^2 and \mathbf{S}^{-1} (when it exists) are

$$\begin{aligned}\mathbf{S}^2 &= \lambda_1^2 \mathbf{e}_1^* \otimes \mathbf{e}_1^* + \lambda_2^2 \mathbf{e}_2^* \otimes \mathbf{e}_2^* + \lambda_3^2 \mathbf{e}_3^* \otimes \mathbf{e}_3^*, \\ \mathbf{S}^{-1} &= \lambda_1^{-1} \mathbf{e}_1^* \otimes \mathbf{e}_1^* + \lambda_2^{-1} \mathbf{e}_2^* \otimes \mathbf{e}_2^* + \lambda_3^{-1} \mathbf{e}_3^* \otimes \mathbf{e}_3^*.\end{aligned}$$

5. Show that

$$\begin{aligned}u_i v_j w_k \{[\mathbf{T}e_i, e_j, e_k] + [e_i, \mathbf{T}e_j, e_k] + [e_i, e_j, \mathbf{T}e_k]\} = \\ \epsilon_{ijk} u_i v_j w_k \{[\mathbf{T}e_1, e_2, e_3] + [e_1, \mathbf{T}e_2, e_3] + [e_1, e_2, \mathbf{T}e_3]\}\end{aligned}$$