

Indian Institute of Science, Bangalore

ME 243: Midsemester Test

Date: 27/9/14.

Duration: 2.30 p.m.–4.00 p.m.

Maximum Marks: 100

1. Let $\{\mathbf{p}_i\}$ and $\{\mathbf{q}_i\}$, $i = 1, 2, 3$, be sets of vectors in \mathfrak{R}^3 . Determine if the set $\{\mathbf{p}_i \otimes \mathbf{q}_i\}$, $i = 1, 2, 3$, is linearly dependent or independent if (25)
 - (a) $\{\mathbf{p}_i\}$ is linearly independent, and $\{\mathbf{q}_i\}$ is linearly independent;
 - (b) $\{\mathbf{p}_i\}$ is linearly independent, but $\{\mathbf{q}_i\}$ is not;
 - (c) $\{\mathbf{q}_i\}$ is linearly independent, but $\{\mathbf{p}_i\}$ is not;
 - (d) $\{\mathbf{p}_i\}$ is linearly dependent, and $\{\mathbf{q}_i\}$ is also linearly dependent.
2. Let $\mathbf{W} \in \text{Skw}$ and let \mathbf{w} be its axial vector. Find the polar decomposition of $\mathbf{I} + \mathbf{W}$ (25) *explicitly*, i.e., the factors \mathbf{R} , \mathbf{U} and \mathbf{V} should be explicit functions of \mathbf{w} and/or \mathbf{W} , which one can compute using a calculator if \mathbf{W} is given in numerical form.
3. Let the underlying vector space dimension be 2, and let $\mathbf{W} \in \text{Skw}$ in this case, i.e., (25)

$$\mathbf{W} = \begin{bmatrix} 0 & \alpha \\ -\alpha & 0 \end{bmatrix}.$$

- (a) Given that the first and last invariants are the trace and the determinant, find an explicit expression for $e^{\mathbf{W}}$, which one can compute using a calculator if α is given.
 - (b) Using this explicit expression, find $De^{\mathbf{W}}(\mathbf{W})[\mathbf{U}]$.
4. Superposed dots denote material time derivatives, and (\mathbf{F}, \mathbf{L}) denote the deformation and velocity gradients. (25)
 - (a) Derive a relation between $\dot{\mathbf{F}}$ and \mathbf{F} .
 - (b) Derive a relation between $\ddot{\mathbf{F}}$ and $\nabla_x \mathbf{a}$, where \mathbf{a} is the acceleration.
 - (c) Using the above relations or independently, find the material derivative of $\nabla_x \cdot \mathbf{v}$ in terms of \mathbf{a} , and possibly \mathbf{L} and \mathbf{F} .

Some relevant formulae

$$\mathbf{W} = |\mathbf{w}|(\mathbf{r} \otimes \mathbf{q} - \mathbf{q} \otimes \mathbf{r}), \quad (\mathbf{w}/|\mathbf{w}|, \mathbf{q}, \mathbf{r} \text{ orthonormal}),$$

$$W_{ij} = -\epsilon_{ijk}w_k, \quad w_i = -\frac{1}{2}\epsilon_{ijk}W_{jk},$$

$$e^{\mathbf{T}} = \mathbf{I} + \mathbf{T} + \frac{1}{2!}\mathbf{T}^2 + \dots,$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} + \dots,$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} + \dots.$$