## Indian Institute of Science, Bangalore ME 243: Midsemester Test

Date: 28/11/20. Duration: 2.00 p.m.–5.00 p.m. Maximum Marks: 100

1. Let  $\boldsymbol{W} \in \text{Skw}$ , and let  $\boldsymbol{w}$  be its axial vector. Find the dimension of  $\text{Lsp}\left\{\boldsymbol{I}, \frac{\boldsymbol{W}}{|\boldsymbol{w}|}, \frac{\operatorname{cof} \boldsymbol{W}}{|\boldsymbol{w}|^2}\right\}$  (40) (Hint: Find  $\operatorname{cof} \boldsymbol{W}$  in terms of  $\boldsymbol{w}$ ). Using this result (and without using some other method), find the dimension of  $\text{Lsp}\{\boldsymbol{I}, \boldsymbol{R}, \boldsymbol{R}^T\}$  for all possible values of  $\alpha$ , where

$$oldsymbol{R} = oldsymbol{I} + rac{\sinlpha}{|oldsymbol{w}|}oldsymbol{W} + rac{(1-\coslpha)}{|oldsymbol{w}|^2}oldsymbol{W}^2$$

In case, the dimension of Lsp{ $I, R, R^T$ } for some particular value  $\alpha = \alpha_0$  is different than for other values of  $\alpha$ , find the dimension corresponding to  $\alpha = \alpha_0$ .

- 2. Consider the following problem :
  - (a) Starting from the equation for rigid motion  $\chi = Q(t)X + c(t)$ , find the expressions for the velocity and acceleration fields in the Eulerian setting.
  - (b) The rigid rod AB of length L shown in Fig. 1 slides against a wall as shown. The angle  $\theta(t)$  as a function of time t is given. You may assume the axial vector of  $\dot{Q}Q^T$  to be given by  $-\dot{\theta}(t)e_z$  (with a superposed dot denoting a derivative with respect to time), where  $e_z = e_x \times e_y$ . Using the results of part (a) above, find the velocity and acceleration of the center point of the rod C as a function of L,  $\theta(t)$  and its derivatives with respect to time. If you make any assumptions about the accelerations of points A and B, kindly justify. You may treat this as a two-dimensional problem, i.e., the motion is in the x-y plane.
- 3. Let  $\boldsymbol{W} \in \text{Skw}$ , and let  $\boldsymbol{w}$  be its axial vector.
  - (a) Does  $W^2 \in \text{Sym}$ ?
  - (b) Assuming  $\mathbf{W} = |\mathbf{w}| (\mathbf{r} \otimes \mathbf{q} \mathbf{q} \otimes \mathbf{r}), (\mathbf{w}/|\mathbf{w}|, \mathbf{q}, \mathbf{r} \text{ orthonormal})$ , and using the result of part (a), find the eigenvalues and eigenvectors of  $e^{(\mathbf{W}^2)}$ . If the eigenvectors are not unique, *choose* an orthonormal set of eigenvectors in terms of  $\mathbf{w}, \mathbf{q}$  and  $\mathbf{r}$ , and state your choice.
  - (c) Let  $I_i$ , i = 1, 2, 3, be the principal invariants of  $e^{(\mathbf{W}^2)}$ . Find the gradients  $\partial I_i / \partial \mathbf{W}$ , i = 1, 2, 3, in terms of  $\mathbf{W}$ .

## Some relevant formulae

$$\begin{split} \boldsymbol{W} &= |\boldsymbol{w}| \left(\boldsymbol{r} \otimes \boldsymbol{q} - \boldsymbol{q} \otimes \boldsymbol{r}\right), \quad (\boldsymbol{w}/|\boldsymbol{w}|, \boldsymbol{q}, \boldsymbol{r} \text{ orthonormal}), \\ &(\mathbf{cof} \, \boldsymbol{T})^T = I_2 \boldsymbol{I} - (\operatorname{tr} \boldsymbol{T}) \boldsymbol{T} + \boldsymbol{T}^2, \\ &W_{ij} = -\epsilon_{ijk} w_k, \\ &w_i = -\frac{1}{2} \epsilon_{ijk} W_{jk}, \\ \boldsymbol{R}(\boldsymbol{w}, \alpha) &= \boldsymbol{I} + \frac{1}{|\boldsymbol{w}|} \sin \alpha \, \boldsymbol{W} + \frac{1}{|\boldsymbol{w}|^2} (1 - \cos \alpha) \boldsymbol{W}^2, \\ &(\mathbf{cof} \, \boldsymbol{T})_{ij} = \frac{1}{2} \epsilon_{imn} \epsilon_{jpq} T_{mp} T_{nq}, \end{split}$$

(35)

(25)



Figure 1: Rigid rod sliding against a wall.