## Indian Institute of Science, Bangalore ME 243: Midsemester Test

Date: 5/10/02. Duration: 9.30 a.m.–11.00 a.m. Maximum Marks: 100

1. Prove that if T : S = 0 for every symmetric tensor S, then  $T \in Skw$ . (15)

(25)

2. Deriving any results that you might need on the way, show that

$$\boldsymbol{R}(\boldsymbol{w},\alpha) = \boldsymbol{I} + \frac{1}{|\boldsymbol{w}|} \sin \alpha \, \boldsymbol{W} + \frac{1}{|\boldsymbol{w}|^2} (1 - \cos \alpha) \boldsymbol{W}^2,$$

where  $\boldsymbol{W}$  is the skew-symmetric tensor with  $\boldsymbol{w}$  as the axis, rotates any vector in the plane perpendicular to  $\boldsymbol{w}$  through an angle  $\alpha$ .

- 3. Our goal in this problem is to find explicit expressions for  $\mathbf{R}$  and  $\mathbf{U}$  in the polar decompostion  $\mathbf{S} = \mathbf{R}\mathbf{U}$ , where  $\mathbf{S}$  is a *nonsingular* symmetric tensor, in terms of powers of  $\mathbf{S}$ .
  - (a) Let V be an n-dimensional vector space with  $\{e_1, e_2, \ldots, e_n\}$  as a basis, and let  $\{f_1, f_2, \ldots, f_n\}$  be given by

$$\boldsymbol{f}_i = \beta_{ij} \boldsymbol{e}_j, \quad \beta_{ij} \in \Re, \ i, j = 1, n,$$

where  $\beta_{ij}$  are such that det  $[\beta_{ij}] \neq 0$ . We have shown in class that under such conditions,  $\{f_1, f_2, \ldots, f_n\}$  is a basis. Hence, we can express the basis vectors  $\{e_1, e_2, \ldots, e_n\}$  in terms of the basis vectors  $\{f_1, f_2, \ldots, f_n\}$  as

$$\boldsymbol{e}_i = \gamma_{ij} \boldsymbol{f}_j, \quad \gamma_{ij} \in \Re, \ i, j = 1, n.$$

Show that  $\gamma_{ij}\beta_{jm} = \delta_{im}$ , i.e., the matrix of coefficients  $[\gamma_{ij}]$  is the inverse of the matrix of coefficients  $[\beta_{ij}]$ .

(b) Starting with the spectral resolution of  $\boldsymbol{S} \in \text{Sym}$ , namely,

$$oldsymbol{S} = \lambda_1 oldsymbol{e}_1^st \otimes oldsymbol{e}_1^st + \lambda_2 oldsymbol{e}_2^st \otimes oldsymbol{e}_2^st + \lambda_3 oldsymbol{e}_3^st \otimes oldsymbol{e}_3^st,$$

find the spectral resolutions of R and U (Hint: Look for tensors of the form

$$|\lambda_1| e_1^* \otimes e_1^* + |\lambda_2| e_2^* \otimes e_2^* + |\lambda_3| e_3^* \otimes e_3^*.$$

- (c) Consider the case when the two eigenvalues are repeated, say,  $\lambda_2 = \lambda_3$ . Express  $\{I, S\}$  in terms of  $\{e_1^* \otimes e_1^*, (e_2^* \otimes e_2^* + e_3^* \otimes e_3^*)\}$ , in the form  $f_i = \beta_{ij}e_j$ , and show that det  $[\beta_{ij}] \neq 0$ . Now using the result of (a), express  $\{e_1^* \otimes e_1^*, (e_2^* \otimes e_2^* + e_3^* \otimes e_3^*)\}$  in terms of  $\{I, S\}$ .
- (d) Substitute these expressions in the polar resolutions of  $\mathbf{R}$  and  $\mathbf{U}$  (for the case  $\lambda_2 = \lambda_3$ ), and find explicit expressions for  $\mathbf{R}$  and  $\mathbf{U}$  as a polynomial expression involving powers of  $\mathbf{S}$ .
- 4. Using the relations  $DJ/Dt = J(\nabla \cdot v)$ , DF/Dt = LF, and  $C = F^t F$ , show that (25)

$$\frac{DJ}{Dt} = \frac{1}{2}J\boldsymbol{C}^{-1}: \dot{\boldsymbol{C}}$$