Mechanics of Microsystems : Micro/nano Mechanics (NE 211) Course Project

Coding isothermal Reynolds equation in Matlab and comparing with analytical solution for the 'OOOO' boundary condition

> More S. K. Cense – M.Tech

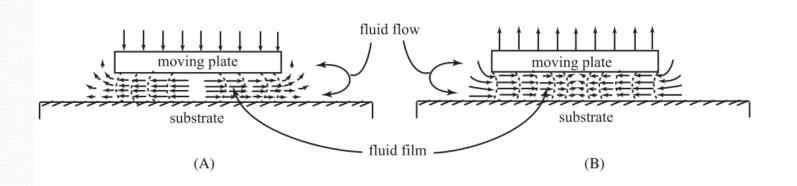
Outline

- •What is Squeeze Film Damping
- •What is the Governing Equation
- •FE formulation
- Formulation of Matlab Code
- •Results

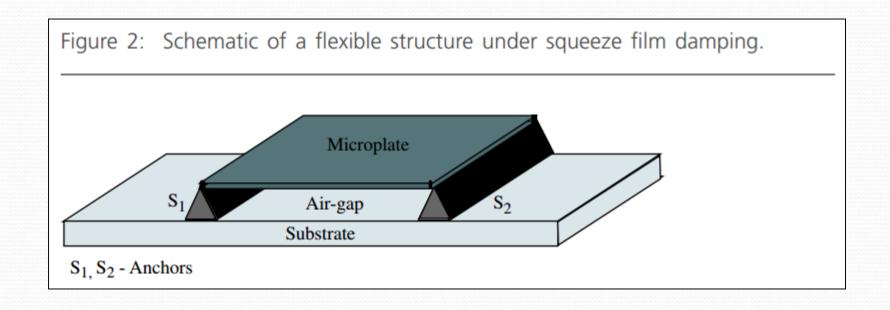
- Cavities, filled with air or some other gas, are common in MEMS.
- Squeeze film effect is natural in such devices.

Consider a air gap between movable plate and fixed underlying structure.

Figure 4: A schematic diagram of squeeze film flow (A) downward normal motion; (B) upward normal motion.²⁰

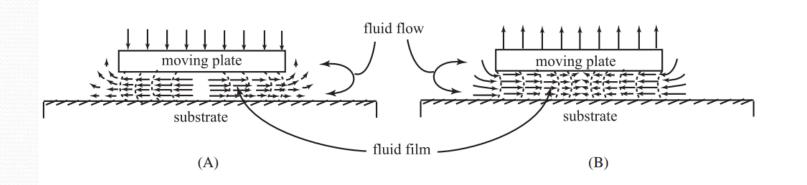


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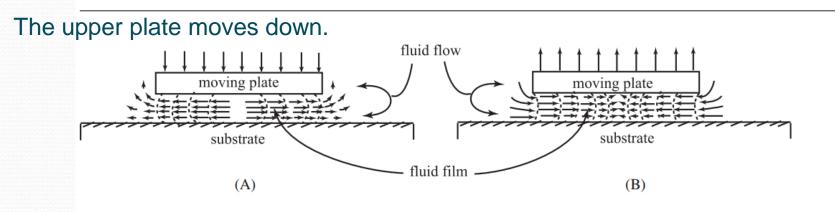
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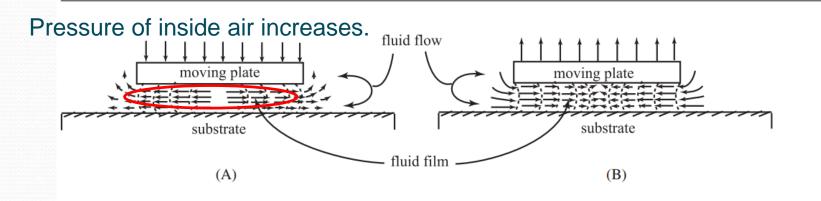
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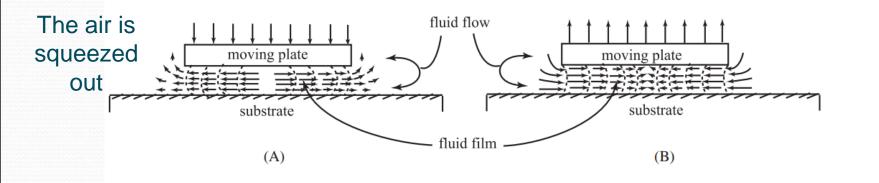
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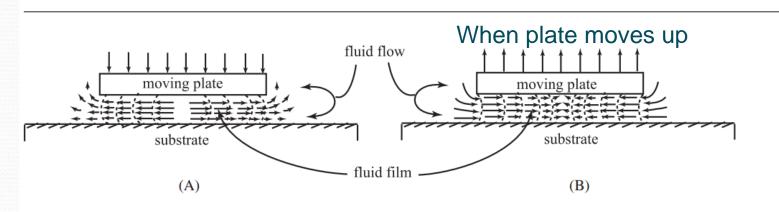
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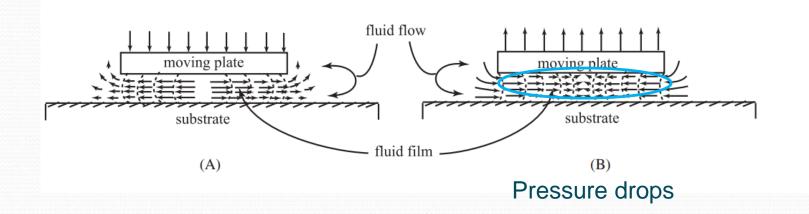
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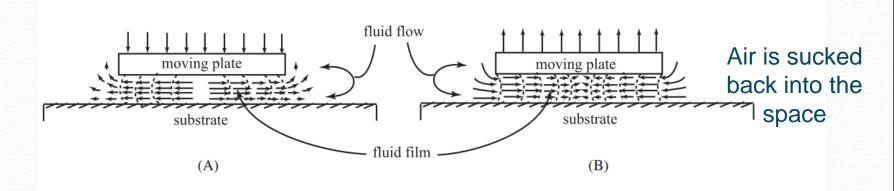
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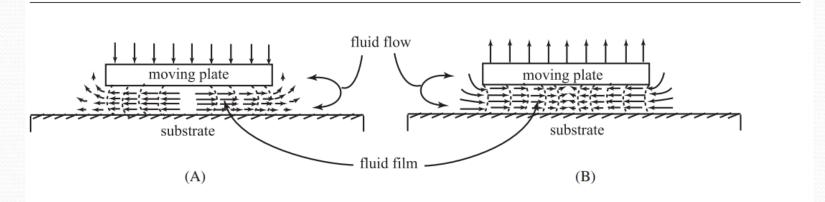
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The viscous drag during the flow creates a dissipative mechanical force on the plate opposing the motion. This dissipative force is called Squeeze Film Damping

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The behavior of trapped gas film at different frequencies of vibration of the plate is of particular interest

• For slow motions of moving plate the effect of the squeezed film is pure damping force, independent of pressure.

• The fluid motion is in phase with the moving plate.

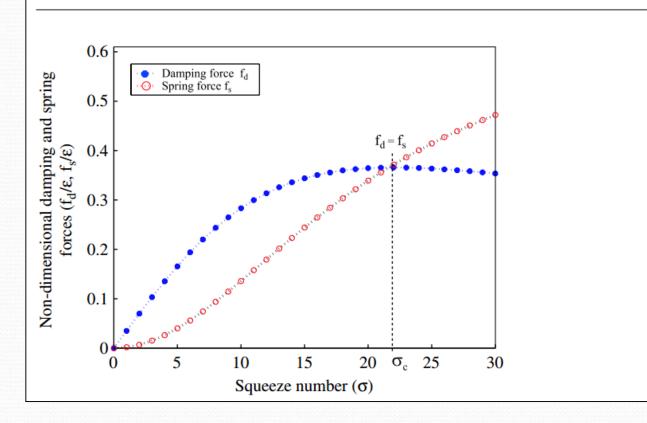
• At higher frequencies of oscillations it often happens that fluid motion lags the plate motion by complete 180deg

• In such a case fluid can't escape from the cavity even if the boundary is open.

• The squeeze film behaves like a spring.

Squeeze Film Effect

Figure 6: Variation of non-dimensional damping force (f_d/ϵ) and spring force (f_s/ϵ) with squeeze number σ ; the point of intersection of the two curves (i.e., $f_d=f_s$) corresponds to the cut-off squeeze number (σ_c) .



Governing Equation

Linearised Reynolds Equation

Non Dimensionalizing by guessing solutions

$$\frac{\partial^2 \tilde{\rho}}{\partial x^2} + \frac{\partial^2 \tilde{\rho}}{\partial y^2} = \mathcal{O}\left[i \mathcal{S} \phi + i \tilde{\rho}\right]$$

 $X = L \mathcal{X}$ $Y = L \mathcal{Y}$ $\mathcal{E} = \mathcal{L}^2 \mathcal{U}$

 $\tilde{P} = Pressure amplitude$ $\phi = shape of plate$ $\delta = displacement amplitude$ Weak Form or Weighted Integral

$$\int \frac{\partial \tilde{P}}{\partial x_i} \frac{\partial v}{\partial x_i} dx + i\delta \int (\tilde{P} + \phi S) V d\Omega = 0$$

V = weight function

After substituting shape functions for V and Nondimentionalized P

$$\sum_{j=1}^{n} \left[\int_{z \in a} \frac{\partial N_j}{\partial x} + \frac{\partial N_j}{\partial y} + \frac{\partial N_j}{\partial y} + i \delta N_j N_j \right] \tilde{p} = -i\delta S \sum_{j=1}^{n} \left[\int_{z \in a} N_j N_j dx dy \right] \tilde{p}$$

A Roychowdhury, S patra Variational formulation for the Reynolds equation.

Which can be represented in compact for as

 $[K_1 + K_2] \tilde{P} = -\delta K_2 \Phi$

 $[K_1] = [S''] + [S^{22}]$ $[K_2] = i \delta [5^{33}]$

 $[S''] = \int_{\mathcal{D}_{e}} \frac{\partial N_{i}}{\partial x} \frac{\partial N_{j}}{\partial x} dx dy$ = 5'5' <u>2Ni</u> . <u>2Ni</u> d5dn

 $[5^{33}] = \int_{\Omega} NiNj \, dx \, dy$ = SSN; Nj d5 d2

 $\left[S^{22}\right] = \int_{2}^{2N_{1}} \frac{\partial N_{1}}{\partial y} \frac{\partial N_{2}}{\partial y} \frac{\partial Y}{\partial y} \frac{\partial$ $[5^{22}] = \int \int \frac{\partial Ni}{\partial \eta} \frac{\partial Nj}{\partial \eta} ds d\eta$

Shape Functions for Bilateral Square Element in Natural Coordinate System

$$\begin{split} N_{1} &= \frac{1}{4} (1-5) (1-2) \\ N_{2} &= \frac{1}{4} (1+5) (1-2) \\ N_{3} &= \frac{1}{4} (1+5) (1-2) \\ N_{4} &= \frac{1}{4} (1-5) (1+2) \end{split}$$

$$(0,b) = \frac{(a,b)}{(a,c)} = \frac{2x}{a} - 1$$

$$(0,c) = \frac{2y}{b} - 1$$

$$(-1,1) = \frac{(-1,-1)}{(1,-1)}$$

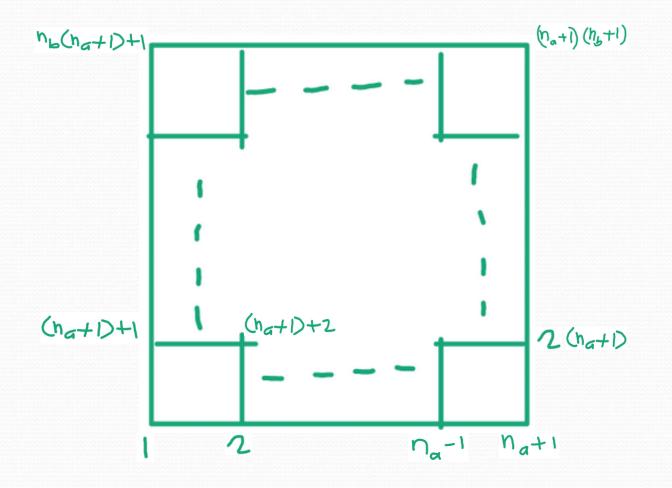
And the change of Coordinates

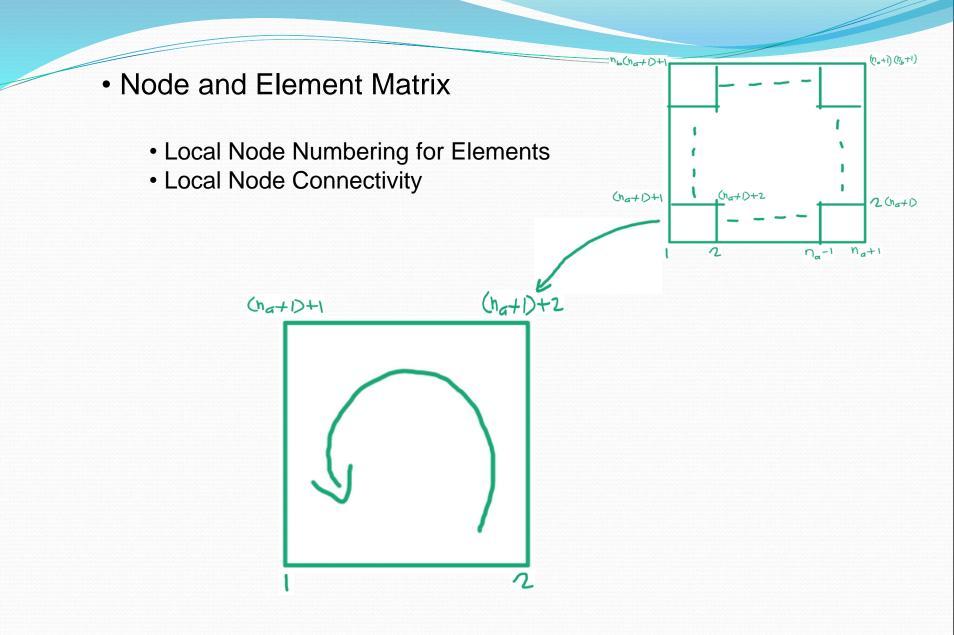
$$\frac{\partial N}{\partial x} = \frac{\partial N}{\partial y} \frac{\partial S}{\partial x} + \frac{\partial N}{\partial y} \frac{\partial N}{\partial x} \qquad J = \begin{bmatrix} \frac{\partial N}{\partial S} & \frac{\partial N}{\partial S} \\ \frac{\partial N}{\partial y} & \frac{\partial N}{\partial S} & \frac{\partial S}{\partial y} + \frac{\partial N}{\partial y} \frac{\partial N}{\partial y} \\ \frac{\partial N}{\partial y} & \frac{\partial N}{\partial S} & \frac{\partial S}{\partial y} + \frac{\partial N}{\partial y} \frac{\partial N}{\partial y} \end{bmatrix}$$

Flow Chart for FEA solution of Reynolds equation

- Preprocessing
 - Node and Element Matrix
 - Contain Global and Local coordinates of nodes
 - Nodal connectivity of Elements
 - Apply Boundary Conditions
 - i.e. Save all nodes which are constrained.
 - Save all nodes other than constrained in different matrix
 - Prepare Mode Shape Matrix
 - Node Displacements according to first mode shape

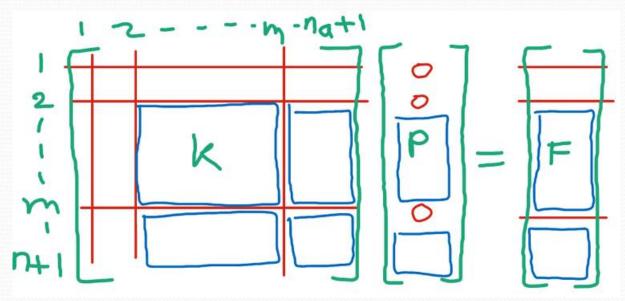
Node and Element Matrix





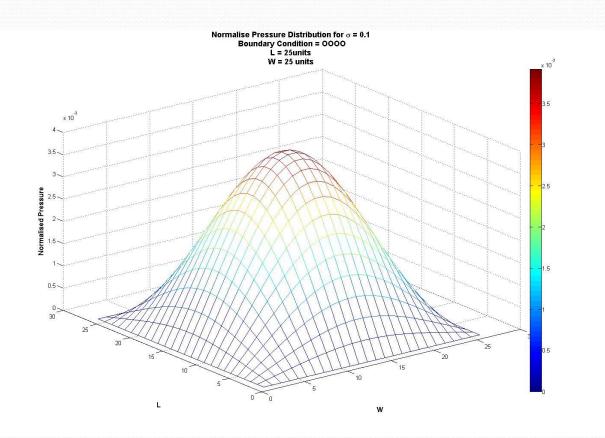
- Building Element Matrix
 - Element Matrix for each element
 - Assembly of all element matrices in Global Matrices K1_g and K2_g
 - Building Global Force matrix

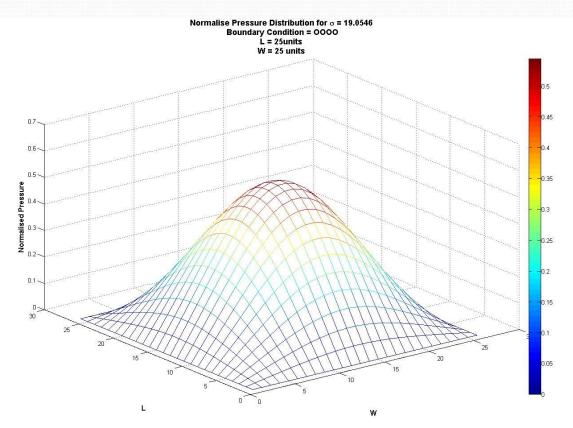
- Solving
 - Applying Boundary Conditions.

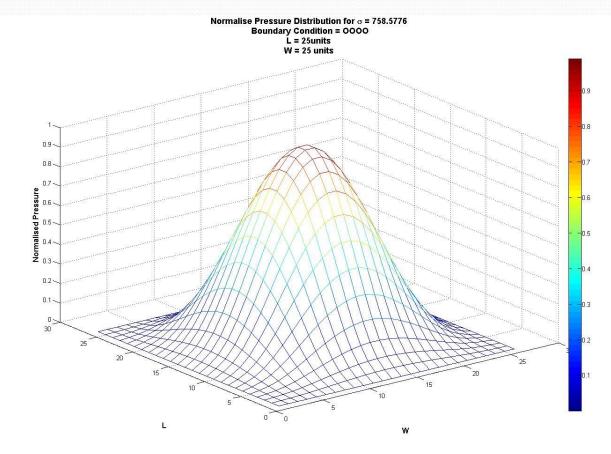


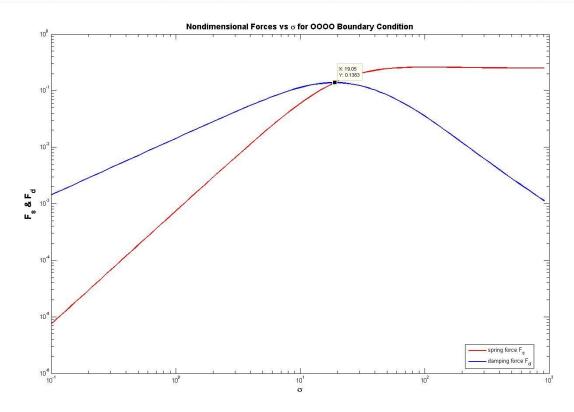
• Solving for Pressure distribution.

$${P} = [K] / {F}$$









References

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- A Roychowdhury, S patra Variational formulation for the Reynolds equation.
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