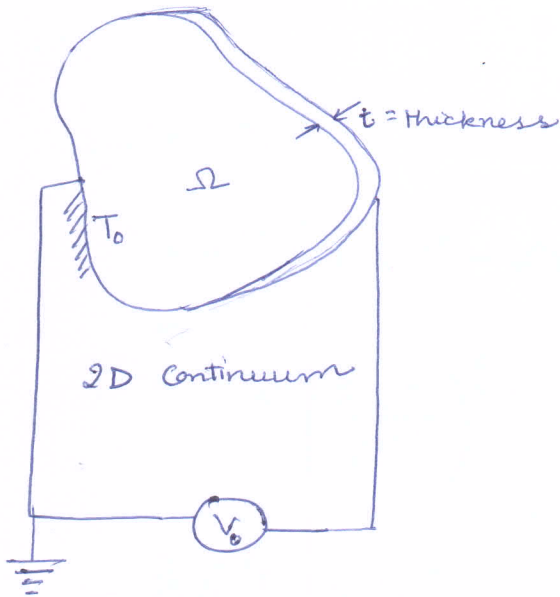


Recap

* Implementation details of the optimality criteria method

- Handling the bounds on $A(x)$
- finding Δ in the inner loop



Electrical conductivity

$$\nabla \cdot (k_e \nabla V) = 0 \quad \text{--- (1)}$$

Thermal conductivity

$$\nabla \cdot (k_m \nabla \phi) + \underbrace{(k_e \nabla V) \cdot \nabla V}_{\text{Joule heating}} = 0$$

$$\phi = T - T_0$$

↳ ambient temp

Phonons (equivalent of e^- as (in electrical) in ~~the~~ thermo)

↳ not a physical thing

So if we have FEM for (1), we get ∇V , then ϕ then Temp.

Now we will like to measure thermal stresses, as deformation are restricted.

$$\nabla \cdot (\bar{D} \bar{E} - \bar{D} \bar{E}_m) = 0$$

where $\bar{E}_m = \alpha \phi \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$

thermal expansion coeff

$$\bar{E} = \frac{\nabla \bar{u} + \nabla \bar{u}^T}{2} = \begin{bmatrix} \frac{d\bar{u}_x}{dx} \\ \frac{d\bar{u}_y}{dy} \\ \frac{1}{2} \left(\frac{d\bar{u}_y}{dx} + \frac{d\bar{u}_x}{dy} \right) \end{bmatrix}$$

$$\text{Min } SE \quad \int_{\Omega} \frac{1}{2} \underbrace{\bar{\mathbf{E}}^T \bar{\mathbf{D}} \bar{\mathbf{E}}}_{\text{Stress}} d\Omega$$

$$0 \leq \rho(\bar{x}) \leq 1$$

subject to

$$\Gamma_u: \int_{\Omega} \bar{\mathbf{E}}^T \bar{\mathbf{D}} \bar{\mathbf{E}}_v t d\Omega - \int_{\Omega} \bar{\mathbf{E}}_m^T \bar{\mathbf{D}} \bar{\mathbf{E}}_v t d\Omega = 0$$

$$\Gamma_\phi: \int_{\Omega} \nabla^T \phi k_m \nabla \phi_v t d\Omega + \int_{\Omega} \nabla v^T k_e \nabla v \phi_v t d\Omega = 0$$

$$\Gamma_v: \int_{\Omega} \nabla v^T k_e \nabla v_v t d\Omega = 0$$

$$\Delta: \int_{\Omega} \rho d\Omega - V^* \leq 0$$

$$\rho(\bar{x}) = \rho(x, y)$$

↳ indicator function / fictitious density

↳ It indicates the presence & absence of the material.

$$D = \rho^{\eta} D_0$$

$$\eta \geq 3$$

↳ this will help to push the value of ρ close of zero toward zero and those close to 1 towards 1.

$$k_m = \rho^{\eta} k_{m0}$$

$$k_e = \rho^{\eta} k_{e0}$$

$$\alpha = \rho^{\eta} \alpha_0$$

Data: $\Omega, \bar{\mathbf{D}}_0, k_{m0}, k_{e0}, \alpha_0, T_0, V^*, t$

7 diff eqⁿ,

unknown fn; $\rho, \phi_v, \phi, u, v, v_v, V$

$$\bar{\mathbf{E}}_v = \begin{bmatrix} \frac{dv_x}{dx} \\ \frac{dv_y}{dy} \\ \frac{1}{2} \left(\frac{dv_x}{dy} + \frac{dv_y}{dx} \right) \end{bmatrix}$$

$v = \delta u$ (Variation of u)

See how to get weak form from strong form.