

## Dynamic loading

$$\text{Min}_{A(x)} \int_0^T \int_0^L P(x, t) u(x, t) dx dt$$

Subject to

$$h(x, t): \underbrace{(EAu')' + p(x, t)}_{EAu' + EAu''} + p_A(x) \ddot{u} + \frac{bi}{\zeta} \dot{u} = 0$$

$\zeta$  Damping

$$\Delta \int_0^L A dx - V^* \leq 0$$

Data:  $E, p(x, t), \rho, b, V^*, L, T$

$$\delta_u L = 0$$

$$P - (EA')' - ib + (\zeta EA)'' + (\zeta p_A)'' = 0$$

$$P - (EA')' - ib + (\zeta EA)'' + \zeta p_A = 0$$

$$\begin{matrix} P + (\zeta EA)' - bi + \zeta p_A = 0 \\ \hline \hline \end{matrix} \quad \text{Adjoint Eq}$$

So in order match adjoint eq<sup>n</sup> with Gov eq<sup>n</sup> then

integrating G.E  $\int_z^0 \boxed{\zeta = -T}$

It's like if we discretize w.r.t time then we will have

$$\text{Adj}_1 \text{ Adj}_2 - \dots - \text{Adj}_{10}$$

so those adjoint equations need to be solved in reverse order.