

Recitation 2a

Principle of minimum potential energy

ME260 Indian Institute of Science

Structural Optimization: Size, Shape, and Topology

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Principle of minimum potential energy

“A mechanical system has minimum potential energy in its stable static equilibrium position.”

This is an alternative view to force balance.

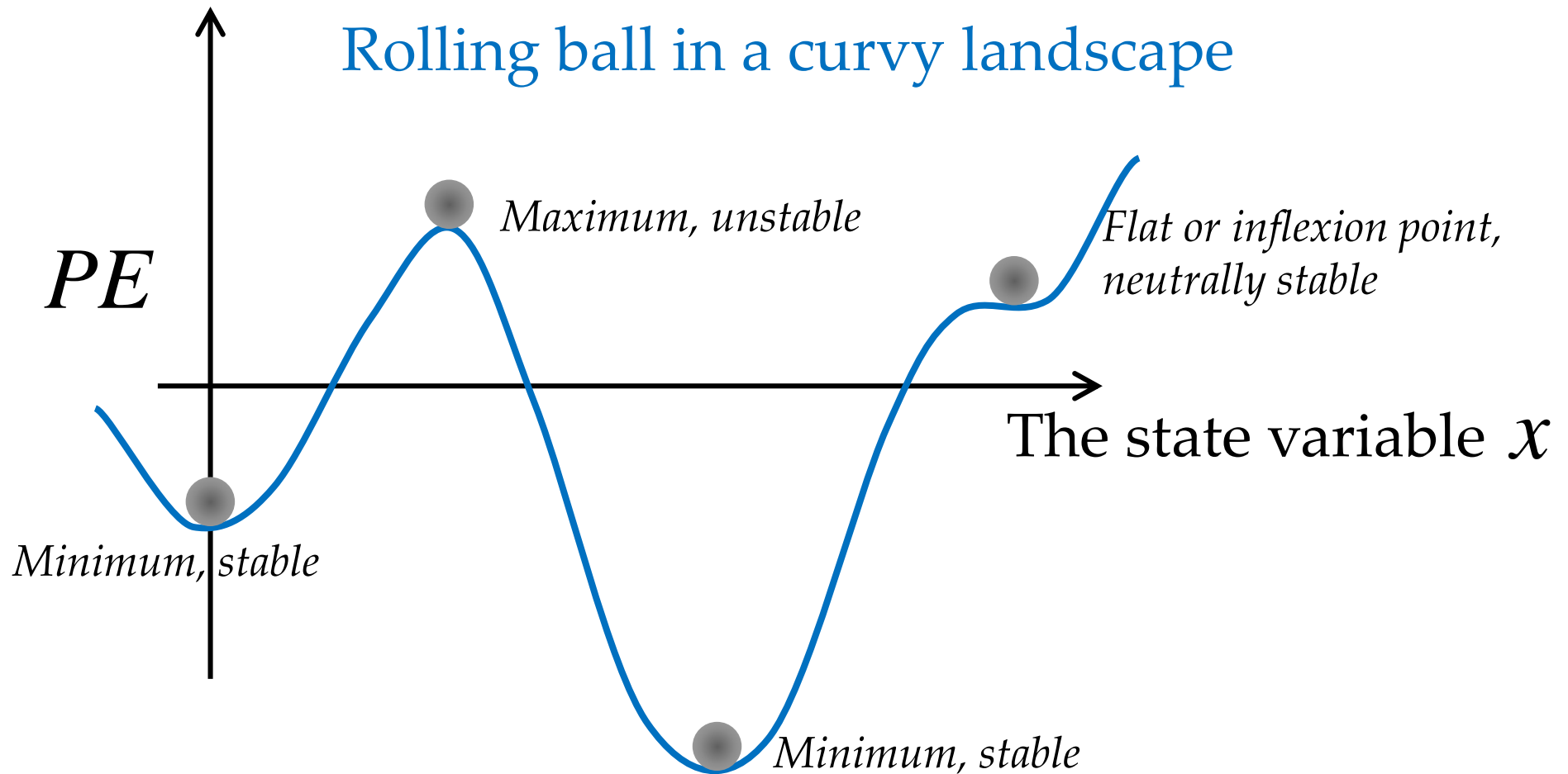
Potential energy = PE = SE + WP

SE = strain energy

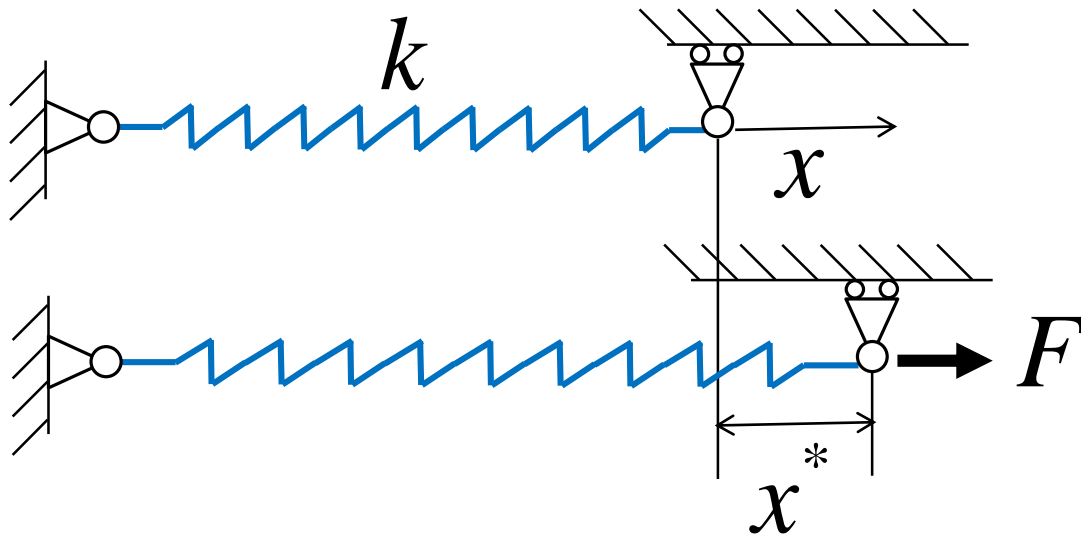
WP = negative of the work done by external forces

This principle involves only energy and work terms. So, it is completely scalar whereas force balance is a vectorial version.

Graphical portrayal of the principle of optimum potential energy



A simple example



We know from force balance:

$$F = kx^*$$

$$\text{Min}_x PE = \frac{1}{2} kx^2 - Fx$$

$$\frac{\partial PE}{\partial x} = kx - F = 0$$

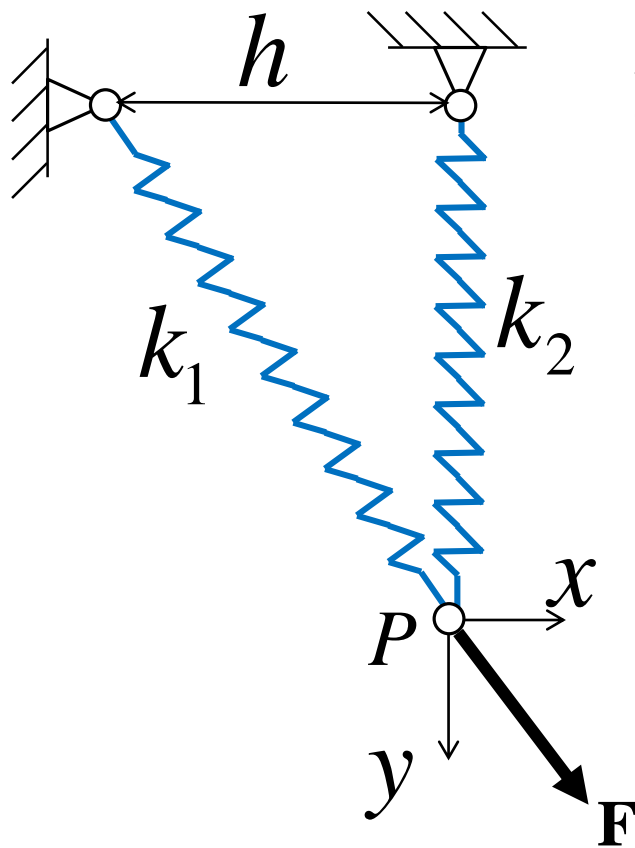
$$\text{So, } F = kx^*$$

$$\text{Strain energy} = SE = \frac{1}{2} kx^2$$

$$\text{Work potential} = WP = -Fx$$

$$\text{Potential energy} = PE = SE + WP = \frac{1}{2} kx^2 - Fx$$

Another example



Undeformed (i.e., when there is no force) lengths of the two springs are: l_{10}, l_{20}

x and y are displacements of Point P .

$$SE = \frac{1}{2} k_1 \left\{ \sqrt{(h+x)^2 + (l_{20}+y)^2} - l_{10} \right\}^2 + \frac{1}{2} k_2 \left\{ \sqrt{(x)^2 + (l_{20}+y)^2} - l_{20} \right\}^2$$

$$WP = -\mathbf{F} \cdot (x\mathbf{i} + y\mathbf{j})$$

$$PE = SE + WP$$

$$\mathbf{F} = F \left(\frac{h}{\sqrt{l_{10}^2 + l_{20}^2}} \hat{\mathbf{i}} + \frac{l_{20}}{\sqrt{l_{10}^2 + l_{20}^2}} \hat{\mathbf{j}} \right)$$

Stable equilibrium conditions

$$PE = SE + WP = \frac{1}{2} k_1 \left\{ \sqrt{(h+x)^2 + (l_{20} + y)^2} - l_{10} \right\}^2 + \frac{1}{2} k_2 \left\{ \sqrt{(x)^2 + (l_{20} + y)^2} - l_{20} \right\}^2 - \mathbf{F} \cdot (x\mathbf{i} + y\mathbf{j})$$

Involves a lot of algebra to solve but it is straightforward to do once we write SE and WP.

$$\left. \begin{array}{l} \frac{\partial PE}{\partial x} = 0 \\ \frac{\partial PE}{\partial y} = 0 \end{array} \right\} \begin{array}{l} \text{Equilibrium} \\ \text{equations} \\ \text{(necessary} \\ \text{conditions} \\ \text{for a} \\ \text{minimum} \\ \text{and a} \\ \text{maximum)} \end{array}$$

$$\begin{bmatrix} \frac{\partial^2 PE}{\partial x^2} & \frac{\partial^2 PE}{\partial x \partial y} \\ \frac{\partial^2 PE}{\partial x \partial y} & \frac{\partial^2 PE}{\partial y^2} \end{bmatrix} = \mathbf{H}$$

Hessian should be positive definite is the **sufficient condition**.

There are many solutions to this problem.